



# Parallelizing Pruning-based Graph Structural Clustering

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# 1、 Pruning-based Graph Structural Clustering

- 2. Performance Bottleneck & Challenge
- **3**、 Parallelization & Vectorization
- 4. Experimental Study
- **5**, Conclusion

# **Graph Structural Clustering**

#### Graph Clustering

• group vertices into *clusters*: dense intra connection and sparse inter connection

#### Application

- do recommendations on social networks, web graphs and copurchasing graphs
- Graph Structural Clustering (Our Focus)
  - utilize structural similarity among vertices for clustering
  - identify *clusters* and *vertex roles* (cores, non-cores)

# **Graph Structural Clustering Example**

- Graph Structural Clustering (Our Focus)
  - utilize structural similarity among vertices for clustering
  - identify *clusters* and *vertex roles* (cores, non-cores: hubs, outliers)



# SCAN [Xu+, KDD'07]

- Structural Similarity Computation
  - based on neighbors of two vertices u and v (cosine measure):
    - $sim(u, v) = |N(u) \cap N(v)| / \sqrt{|N(u)| \cdot |N(v)|}$
  - *u* and *v* are *similar neighbors*, if
    - they are connected
    - their *structural similarity*  $sim(u, v) \ge \varepsilon$



# **SCAN** [Xu+, KDD'07]

- Core Checking
  - a vertex *u* is a core, if it has  $\geq \mu$  *similar neighbors*
- Structural Clustering
  - clustering by *similar neighbors* from cores
  - adopting Breadth-First-Search (BFS) for cluster expansion



# SCAN [Xu+, KDD'07]

- Structural Clustering
  - clustering by *similar neighbors* from cores
  - adopting Breadth-First-Search (BFS) for cluster expansion



# pSCAN [Chang+, ICDE'16]

- Pruning Similarity Computations
  - adopt *union-find* data-structure, change algorithmic design
  - avoid *redundant similarity computation*, apply pruning techniques
  - apply *early termination* in similarity computation



 $N(6) = \{5,6,7,8,9\}$   $N(9) = \{6,7,8,9,10,11\}$  $sim(6,9) = 4/\sqrt{5 \cdot 6} \approx 0.73$ 

#### **Motivation of Parallelization**

- Motivation of Parallelizing pSCAN
  - cost too much time for interactive exploration of clustering results
  - cost most from the *set-intersection based similarity computation*



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#### **Time BreakDown (SCAN and pSCAN)**

- Observations
  - *similarity computation* is the performance bottleneck
  - workload reduction of pSCAN is light-weight but useful



**On LiveJournal/Orkut/Twitter** 

# pSCAN Parallelization Challenge

#### Data Dependency

- there exists concurrent access of *lower and upper bounds* of *number of similar neighbors*
- a priority queue for selecting vertex with max upper bound of *similar neighbors* requires heavy synchronization
- owing to the *similarity reuse* technique, similarity values sim(u, v) and sim(v, u) are dependent

#### Clustering Concurrency Issues

- *union-find* operations should be thread-safe
- *cluster id initialization and assignment* should be thread-safe

#### • Workload Skew and Irregularity

- the workload for each vertex depends on its *degree* and *role*
- *pruning techniques* make the workload irregular

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### **Two-Step Multi-Phase Design Overview**

#### • Step 1: Role Computing (Determining Core or Non-Core)

- similarity pruning phase (without similarity computation)
- core checking phase
- core consolidating phase (finalizing roles of all the vertices)
- Step 2: Core and Non-Core Clustering
  - core clustering without similarity computation phase
  - finalizing core clustering with similarity computation phase
  - cluster id initialization phase
  - non-core clustering (cluster id assignment) phase
- Computation Optimizations
  - *degree-based task scheduling*: dealing with the workload skewness
  - *pivot-based set-intersection vectorization*: improving the efficiency of similarity computation

# **Step 1 : Role Computing**



finalizing vertex roles (either *core* or *non-core*), stashing some similarity values (*unknow/similar/not-similar*)

# **Similarity Pruning**

- Utilize Similarity Definition & Min-Max Pruning
  - do not incur set intersections (similarity computations)
  - utilize lower and upper bounds of number of similar neighbors



# **Similarity Pruning**

- Utilize Similarity Definition & Min-Max Pruning
  - do not incur set intersections (similarity computations)
  - utilize lower and upper bounds of number of similar neighbors

```
1 foreach u \in V in parallel do
  Procedure PruneSim(u)
7
                                                                                 PruneSim(u)
                                                                          2
       foreach v \in N(u) do
8
            sim[e(u, v)] \leftarrow Unkown
9
            Update sim[e(u, v)] using the similarity predicate pruning
10
            if sim[e(u, v)] == Sim then
11
                sd \leftarrow sd + 1
12
            else if sim[e(u, v)] == NSim then
13
                                                                             this phase determines
                ed \leftarrow ed - 1
14
                                                                             some vertex roles
                                    lower bound
       if sd \ge \mu then
15
            role[u] \leftarrow Core
                                                                             without similarity
16
       else if ed < \mu then
                                    upper bound
                                                                             computations
17
            role[u] \leftarrow NonCore
18
       else
19
            role[u] \leftarrow Unknown
20
```

local variables *sd* (similar degree) and *ed* (effective degree): *lower and upper bounds* of *u*'s similar neighborhood size

# **Core Checking and Consolidating**

- Vertex Exploration Order Constraint (*u* < *v*):
  - to guarantee no redundant computation: each undirected edge is computed at most once for the similarity value
- Core Checking and Consolidating Two-Phase
  - to apply *similarity reuse* technique given vertex order constraint, while finalizing all vertex roles
  - 3 foreach  $u \in V$  and role[u] == Unknown in parallel do

```
4 | CheckCore(u)

5 foreach u \in V and role[u] == Unknown in parallel do two phases
```

6 ConsolidateCore(u)

after the two parallel phases, *all vertex roles are known* 

# **Core Checking**

3 foreach  $u \in V$  and role[u] == Unknown in parallel do

4 CheckCore(u)

5 foreach  $u \in V$  and role[u] == Unknown in parallel do

6 ConsolidateCore(u)

two phases

#### 21 **Procedure** CheckCore(u)

22	foreach $v \in N(u)$ do		
23	if $sim[e(u, v)] == Sim$ then	1) initialize <i>nruning related</i>	
24	$sd \leftarrow sd + 1$	1) militanze pranting retailed	
25	if $sd \ge \mu$ then	lower and upper bounds, and	
26	$role[u] \leftarrow Core, return$	see if we can benefit from	
27	else if $sim[e(u, v)] == NSim$ then	<i>parallel core checking</i> from	
28	$ed \leftarrow ed - 1$	u's neighbors with the <b>min</b> -	
29	if $ed < \mu$ then		
30	$role[u] \leftarrow NonCore, return$	max pruning technique	
31	<b>foreach</b> $v \in N(u)$ and $u < v$ and $sim[e(u, v)] = = Unknown$ do		
32	$sim[e(v, u)] \leftarrow sim[e(u, v)] \leftarrow CompSim(u, v)$		
33	Update <i>sd</i> , <i>ed</i> and <i>role</i> in the same logic as Lines 23-30		

# **Core Checking**

3 foreach u ∈ V and role[u] == Unknown in parallel do
4 | CheckCore(u)
5 foreach u ∈ V and role[u] == Unknown in parallel do
6 | ConsolidateCore(u)

21 <b>Procedure</b> CheckCore(u)						
22	foreach $v \in N(u)$ do					
23	if $sim[e(u, v)] == Sim$ then	2) determine some vertex roles,				
24	$sd \leftarrow sd + 1$	and apply the similarity rouse and				
25	if $sd \ge \mu$ then	and apply the similarity rease and				
26	$role[u] \leftarrow Core, return$	min-max pruning techniques				
27	else if $sim[e(u, v)] == NSim$ then					
28	$ed \leftarrow ed - 1$					
29	if $ed < \mu$ then					
30	$role[u] \leftarrow NonCore, return$					
31	<b>foreach</b> $v \in N(u)$ and $u < v$ and $sim[e(u, v)] == Unknown$ do					
32	$sim[e(v, u)] \leftarrow sim[e(u, v)] \leftarrow CompSim(u, v)$					
33	Update <i>sd</i> , <i>ed</i> and <i>role</i> in the same logic as Lines 23-30					

# **Core Consolidating**

<ul> <li>s foreach u ∈ V and role[u] == Unknown in parallel do</li> <li>4   CheckCore(u)</li> <li>5 foreach u ∈ V and role[u] == Unknown in parallel do</li> <li>6   ConsolidateCore(u)</li> </ul>
21 <b>Procedure</b> $CheckCore(u)$
22 foreach $v \in N(u)$ do
if $sim[e(u, v)] == Sim$ then
24 $sd \leftarrow sd + 1$
if $sd \ge \mu$ then
26 $role[u] \leftarrow Core, return$
else if $sim[e(u, v)] == NSim$ then
$28 \qquad \qquad ed \leftarrow ed - 1$
29 if $ed < \mu$ then
30 $role[u] \leftarrow NonCore, return$
for each $v \in N(u)$ and $u < v$ and $sim[e(u, v)] == Unknown$ do
32 $sim[e(v, u)] \leftarrow sim[e(u, v)] \leftarrow CompSim(u, v)$
33 Update <i>sd</i> , <i>ed</i> and <i>role</i> in the same logic as Lines 23-30 <i>finalizing all vertex roles</i>
34 Procedure ConsolidateCore(u)
35 Do the same as $CheckCore(u)$ , except for <b>removing the constraint</b>
u <v 31<="" in="" line="" td=""></v>
and affiniance manufer the similarity computation is at most involved once for

*work-efficiency-proof:* the similarity computation is at most invoked once for the similarity values sim[e(u, v)] and sim[e(v, u)]

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# **Step 2 : Core and Non-Core Clustering**



# **Core Clustering**

- Two Phase Separation
  - core clustering using already known similarity values *without set intersections*
  - finalizing core clustering with set intersections
  - 1 foreach  $u \in V$  and role[u] == Core in parallel do
    - ClusterCoreWithoutCompSim(u)

```
two phases
```

- <sup>3</sup> foreach  $u \in V$  and role[u] == Core in parallel do
- 4 ClusterCoreWithCompSim(u)
- Avoiding Redundant Computation
  - adding u < v constraint during the clustering for both phases
  - applying union-find pruning in the second phase
  - 9 Procedure ClusterCoreWithoutCompSim(u)
- 10 **foreach**  $v \in N(u)$  and role[v] == Core and u < v and not IsSameSet(u, v) and sim[e(u, v)] == Sim do 11 Union(u, v)
- 12 **Procedure** *ClusterCoreWithCompSim(u)*
- 13 foreach  $v \in N(u)$  and role[v] == Core and u < v and 14 not IsSameSei(u, v) and sim[e(u, v)] == Unknown do 15 if  $sim[e(u, v)] \leftarrow CompSim(u, v)$ 15 if sim[e(u, v)] == Sim then

*vertex order constraint union-find pruning* 

vertex order constraint

# **Non-Core Clustering**

- Two Phase Separation
  - *cluster id initialization* using atomic operations
  - *non-core cluster id assignment* from all the cores to similar neighbors (to form final results)



### **Degree-based Task Scheduling**

- Dynamic Scheduling
  - vertex computations relate to the degree and role of the vertex in all the phases, for the *exploration of neighbors* and *computations*
  - a task can be represented with  $[v_{beg}, v_{end})$ , and the parameter of range size is tunable (in our experimental setting: 32768)



#### **Set-Intersection Vectorization**

I	<b>nput:</b> $u, v, u$ 's and $v$ 's neighbors (sorted arrays)	
C	<b>Dutput:</b> similarity value of $e(u, v)$	11 1 1
1 C	$u \leftarrow \sqrt{(d[u]+1)(d[v]+1)}, du \leftarrow d[u]+2, dv \leftarrow d[u]+2, cn \leftarrow 2$	pper and lower bounds
2 0	$ff_u \leftarrow off[u], off_v \leftarrow off[v]$	
3 W	vhile <i>true</i> do	
	/* Step1: find the next pivot offset off_u */	
4	<pre>while of f_u + 16 &lt; of f[u + 1] do     /* Load 16 identical integers */</pre>	
5	$pivot_v \leftarrow \_mm512\_set1\_epi32(dst[off\_v])$	
	/* Load 16 integers */	
6	$u\_eles \leftarrow \_mm512\_loadu\_si512(\&dst[off\_u])$	
	/* Mask bit is 1 if <i>pivot_v &gt; u_ele</i> , 0 otherwise */	
7	$mask \leftarrow \_mm512\_cmpgt\_epi32\_mask(pivot\_v, u\_eles)$	
	/* Number of elements $< pivot_v$ */	1. Find the fi
8	$bit\_cnt \leftarrow \_mm\_popcnt\_u32(mask)$	
9	off $u \leftarrow off u + bit cnt, du \leftarrow du - bit cnt$	sorted neighb
10	if du < c then early termination	
11	return NSim	
	/* If not all $u_{ele} < pivot_v$ , we find the $off_u */$	
12	if $bit_cnt < 16$ then	
13	break	
14	if $off_u + 16 \ge off[u+1]$ then	
15	break	
16	/* Step2: find the next pivot offset $off_v$ */ Find the next $off_v$ , satisfying $dst[off_v] \ge pivot_u$ using t	he <b>2. Find the fir</b>
	same logic as Lines 4-13	control workh
17	if $off v + 16 \ge off[v + 1]$ then	sorieu neighb
18	break	
	/* Step3: if find a match, we update $cn$ , $off_u$ , $off_v$	*/
19	if $dst[off u] == dst[off v]$ then	
20	$   cn \leftarrow cn + 1, of f_u \leftarrow of f_u + 1, of f_v \leftarrow of f_v + 1 $	3. Count the
21	<b>if</b> $cn \ge c$ then	
22	return Sim	

1. Find the first element in u's sorted neighbors  $\geq$  pivot\_v

2. Find the first element in v's sorted neighbors  $\geq$  pivot\_u

3. Count the match

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<sup>23</sup> Fall back to the non-vectorized logic to finish the remaining work

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- Environments
  - *Xeon Phi Processor (KNL):* 64 cores (2 VPUs / core), AVX512, 64KB/1024KB L1/L2 caches, 16GB MCDRAM (cache mode), 96GB RAM
  - *Xeon CPU E5-2650*: 20 cores, AVX2, 64KB/256KB/25MB L1/L2/L3 cache, 64GB RAM
- Algorithms
  - Sequential: SCAN [Xu+, KDD'07], pSCAN [Chang+, ICDE'16]
  - Parallel: *anySCAN* [Mai+, ICDE'17], *SCAN-XP* [Takahashi, NDA'17], our *ppSCAN*, *ppSCAN-NO* (without vectorization)
- Graphs (Billion-Edge)
  - Real-World: Orkut/Twitter/Friendster (Social), Webbase (Web)
  - Synthetic Power-Law: *ROLL* Graphs [Hadian+, SIGMOD'16]

### **Overall Performance (on CPU and KNL)**

#### Algorithm Comparison

- SCAN and pSCAN lack parallelization
- SCAN-XP lacks usage of pruning techniques
- *anySCAN* suffers from heavy synchronization and poor memory locality, and runs out of memory on webbase and friendster datasets
- *ppSCAN* has good memory locality and negligible synchronization overheads, and utilizes vectorization AVX2 on CPU and AVX512 on KNL



#### **Set-Intersection Invocation Reduction**

#### • Work Efficiency

- multi-phase computation does not introduce more workload
- ppSCAN even compute less because of the *similarity pruning* and *parallel core checking benefits*



#### **Set-Intersection Vectorization Improvement**

- Core Checking Speedup from Vectorization
  - on CPU: at most 3.5x, on KNL: at most 4.5x
  - vectorization have better performance with more workloads (when memory access is not a bottleneck, e.g., when  $\varepsilon = 0.1$ , *intensive set intersections* hide the *memory access latency*



 $\mu = 5$  (On Both CPU and KNL)

### **Scalability to Number of threads**

#### Scalability and Time Breakdown

- all the four phases scale well to number of threads
- speedup of *core checking* is better than other phases, because the *intensive set intersection computations* hide the *memory access latency*
- time breakdown ratio:
  - core checking and consolidating > similarity pruning > non-core clustering > core clustering



#### Robustness

- Given Different Parameters and Graphs
  - robust on varying input parameters
    - finish computations within 70 seconds



- robust on synthetic graphs (1-billion edge)
  - finish computations within 60 seconds
  - achieve up to 135x self-speedup on KNL



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# Conclusion

#### Parallelization & Vectorization Design

- multi-phase lock-free parallel vertex computations
- dynamic degree-based vertex computation task scheduling
- pivot-based set intersection vectorization

#### • Experimental Study

- *ppSCAN* is about *2x* faster on KNL (64 cores, *AVX512*) than on Xeon CPU (20 cores, AVX2) because of wider SIMD width
- on KNL, *two orders of magnitude* faster than the sequential *pSCAN*
- on KNL, *one order of magnitude* faster than the parallel *anySCAN* and *SCAN-XP*
- on KNL, up to 135x self-speedup (over single-thread *ppSCAN*)

# **End - Q & A**



• Source Codes / Figures / Related Projects : https://github.com/GraphProcessor/ppSCAN



• More Experimental Studies (Scripts / Figures): https://github.com/GraphProcessor/ppSCAN/tree/master/pyt hon\_experiments



# • This PPT:

https://www.dropbox.com/sh/i1r45o2ceraey8j/AAD8V3 WwPElQjwJ0-QtaKAzYa?dl=0&preview=ppSCAN.pdf

